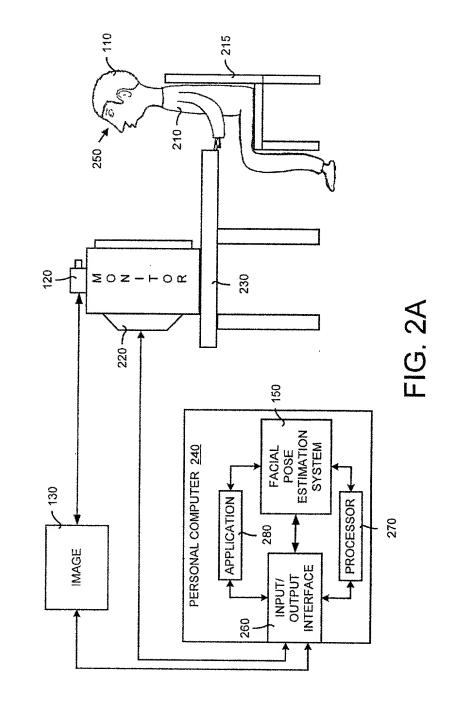
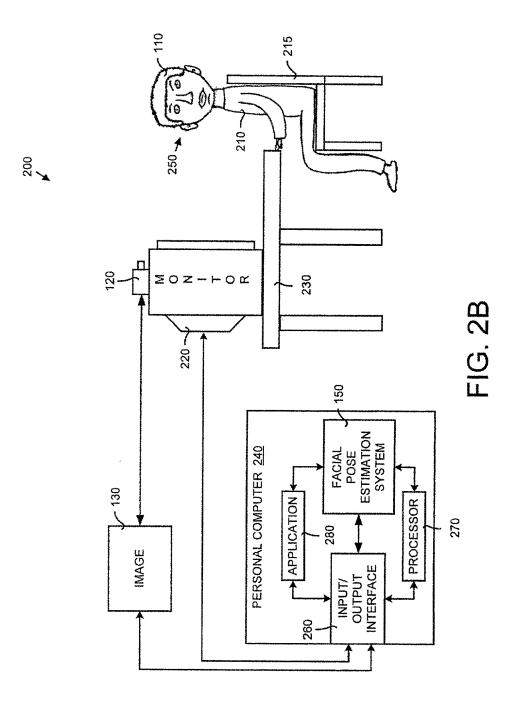
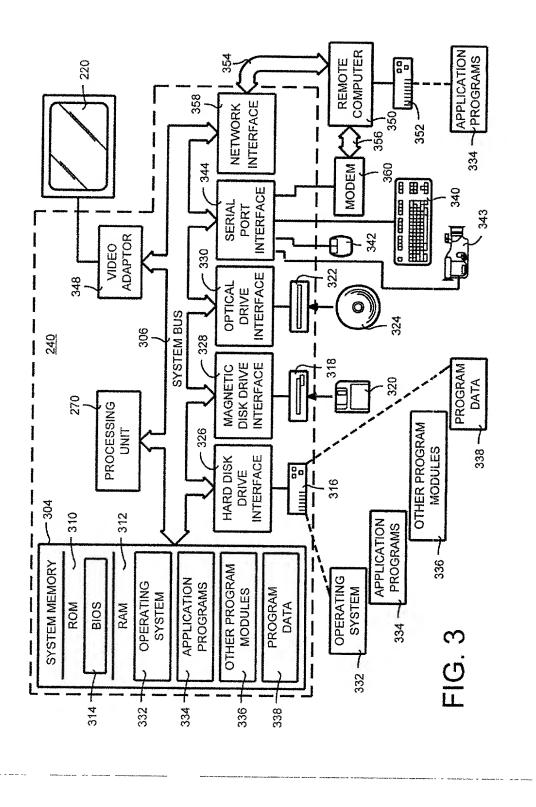


200







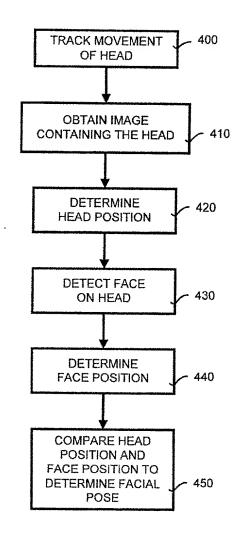
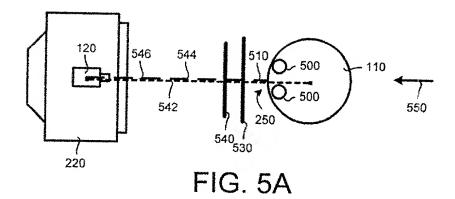
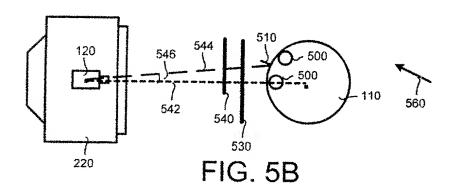
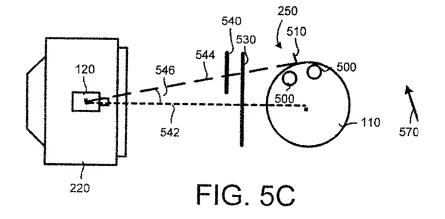


FIG. 4







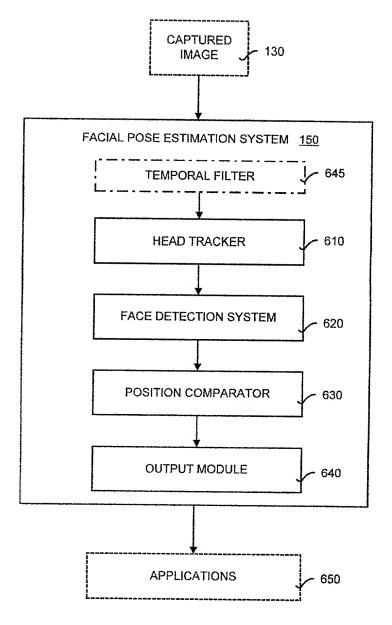


FIG. 6

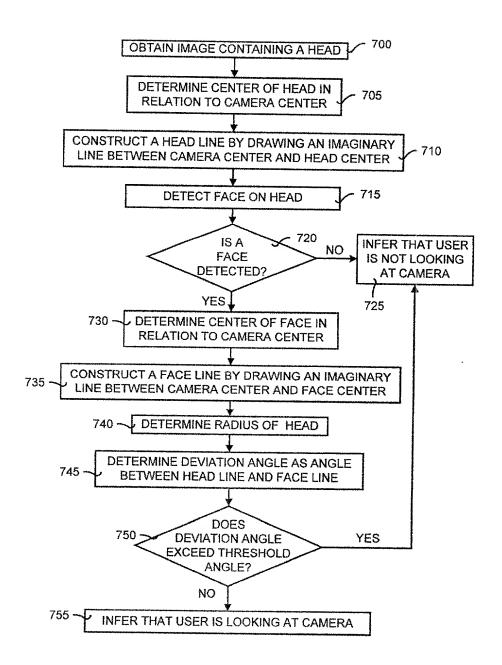
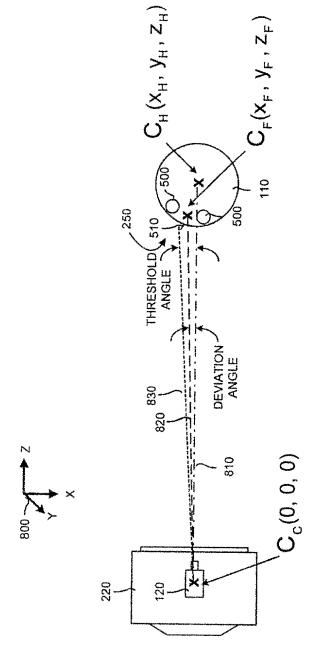


FIG. 7

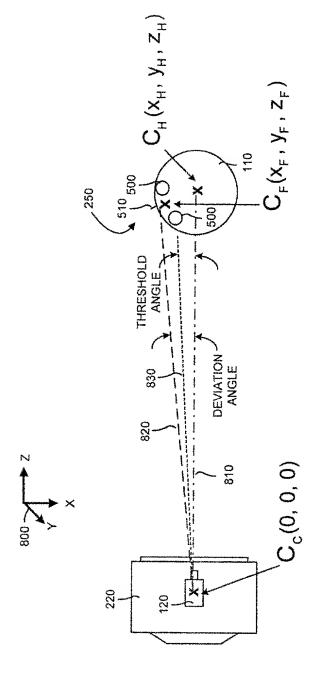
X-Z PLANE (YAW)



DEVIATION ANGLE < THRESHOLD ANGLE ==> USER OBSERVING MONITOR

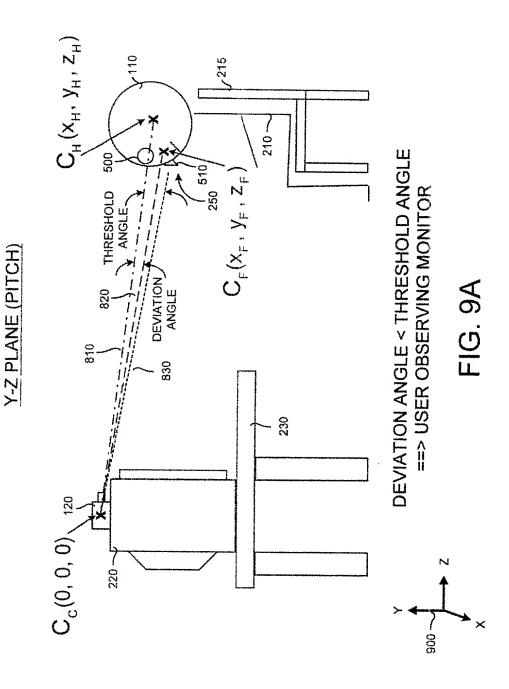
FIG. 8A

X-Z PLANE (YAW)



DEVIATION ANGLE > THRESHOLD ANGLE ==> USER NOT OBSERVING MONITOR

FIG. 8B



Y-Z PLANE (PITCH)

 $\vec{C}_{H}\left(x_{H},\,y_{H},\,z_{H}\right)$ /215 210 -DEVIATION ANGLE > THRESHOLD ANGLE ==> USER NOT OBSERVING MONITOR $C_F(x_F, y_F, z_F)$ THRESHOLD ANGLE DEVIATION Y FIG. 9B 810 820 230 C_c(0, 0, 0)_\ 220~ 1 006

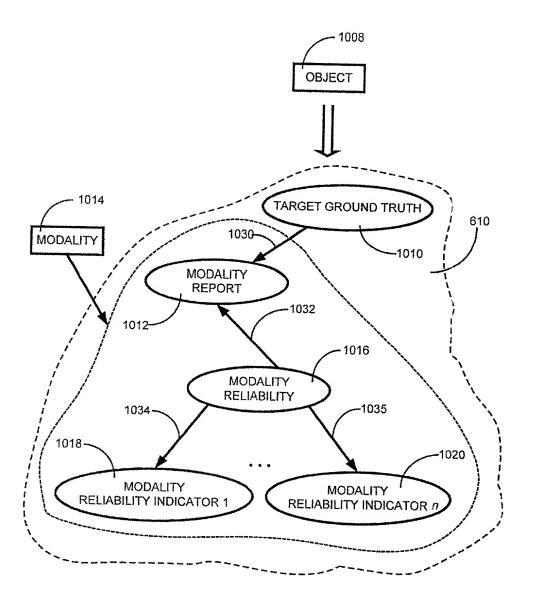


FIG. 10

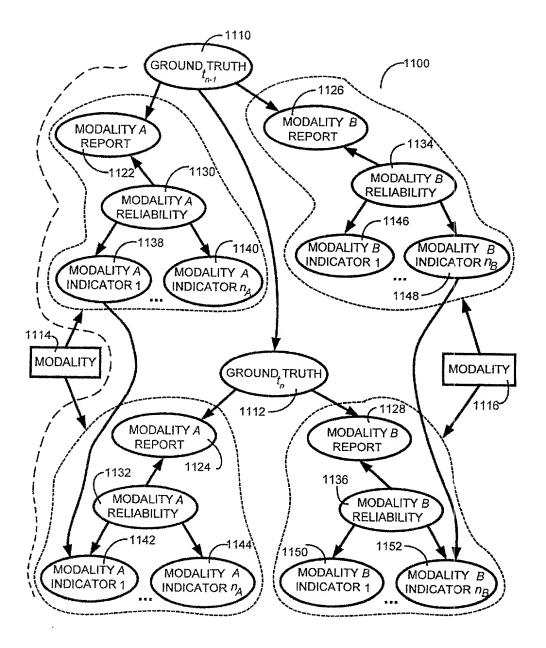


FIG. 11

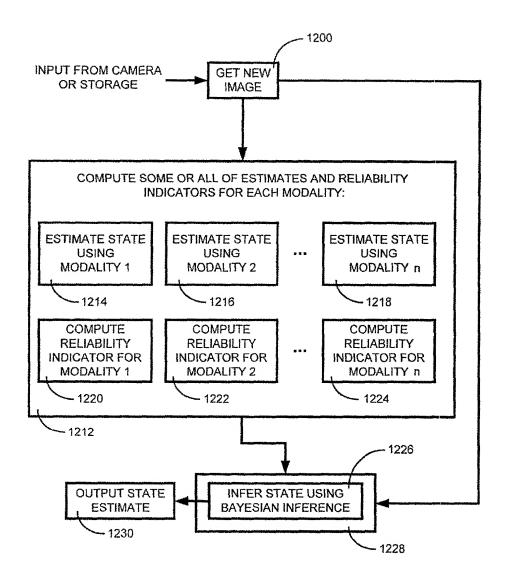


FIG. 12

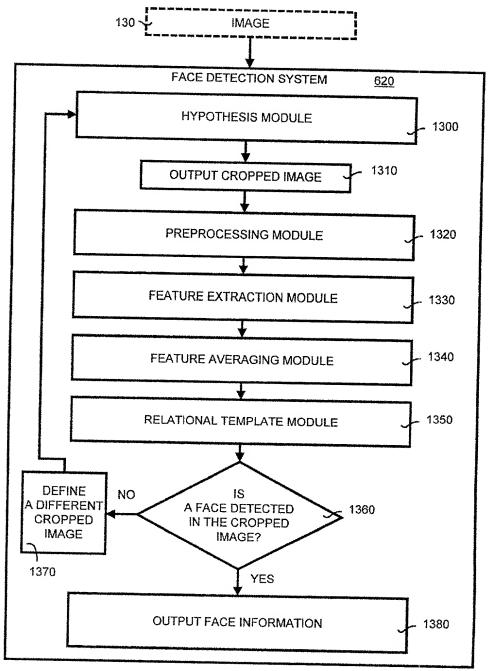


FIG. 13

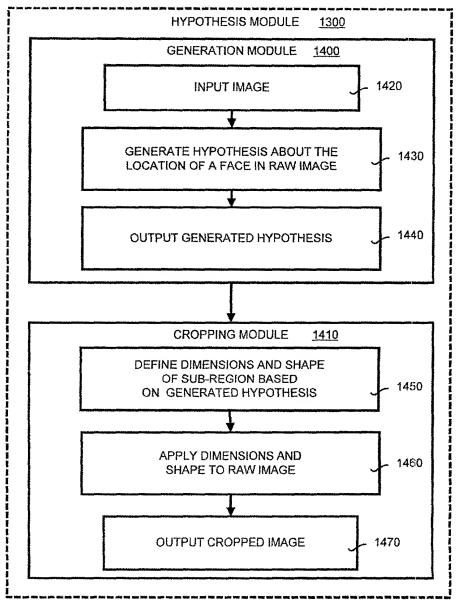


FIG. 14

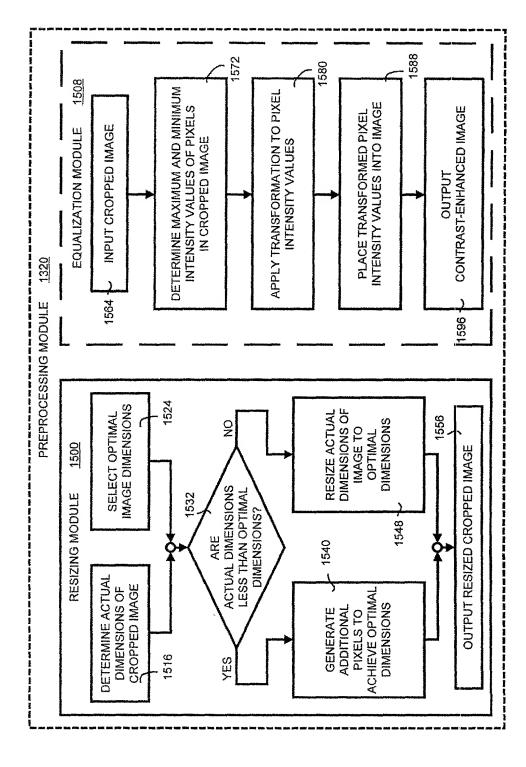


FIG. 15

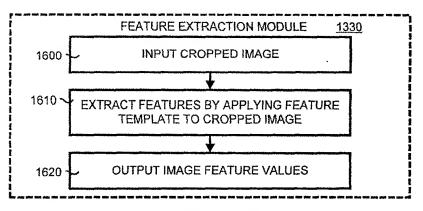


FIG. 16

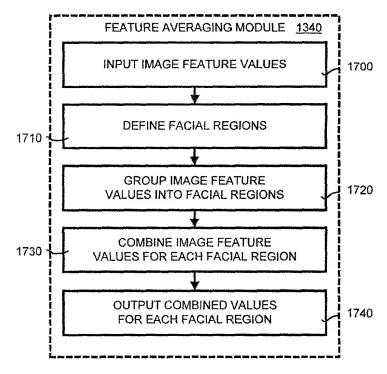


FIG. 17

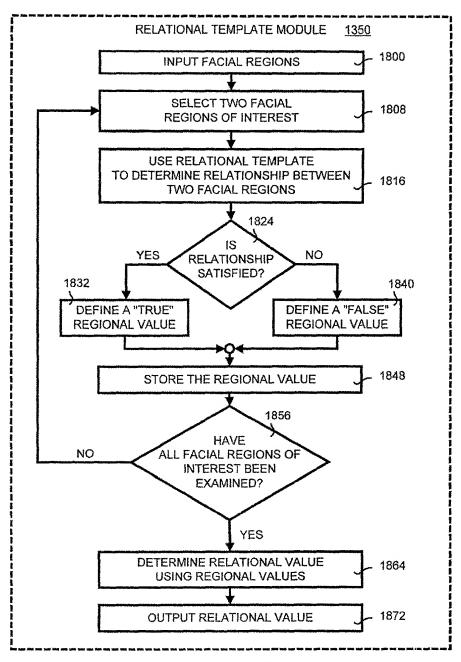


FIG. 18